

Control Flow Analysis

COMP 621 – Program Analysis and Transformations

These slides have been adapted from
<http://cs.gmu.edu/~white/CS640/Slides/CS640-2-02.ppt>
 by Professor Liz White.

Program Control Flow

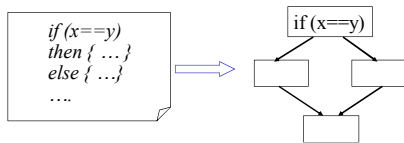
- Control flow
 - Sequence of operations
 - Representations
 - Control flow graph
 - Control dependence
 - Call graph
- Control flow analysis
 - Analyzing program to discover its control structure
 - Today's topic: CFG-based analysis

Control Flow Analysis

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Control Flow Graph

- CFG models flow of control in the program (procedure)
- $G = (N, E)$ as a directed graph
 - Node $n \in N$: basic blocks
 - A basic block is a maximal sequence of stmts with a single entry point, single exit point, and no internal branches
 - For simplicity, we assume a unique entry node n_0 and a unique exit node n_i in later discussions
 - Edge $e=(n_i, n_j) \in E$: possible transfer of control from block n_i to block n_j



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Basic Blocks

- Definition
 - A basic block is a maximal sequence of consecutive statements with a single entry point, a single exit point, and no internal branches
- Basic unit in control flow analysis
- Local level of code optimizations
 - Redundancy elimination
 - Register-allocation

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Basic Block Example

```
(1) i := m - 1
(2) j := n
(3) t1 := 4 * n
(4) v := a[t1]
(5) i := i + 1
(6) t2 := 4 * i
(7) t3 := a[t2]
(8) if t3 < v goto (5)
(9) j := j - 1
(10) t4 := 4 * j
(11) t5 := a[t4]
(12) if t5 > v goto (9)
(13) if i >= j goto (23)
(14) t6 := 4*i
(15) x := a[t6]
...
```

- How many basic blocks in this code fragment?
- What are they?

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Basic Block Example

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...
```

- How many basic blocks in this code fragment?
- What are they?

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Identify Basic Blocks

Input: A sequence of intermediate code statements

- Determine the *leaders*, the first statements of basic blocks
 - The first statement in the sequence (entry point) is a leader
 - Any statement that is the target of a branch (conditional or unconditional) is a leader
 - Any statement immediately following a branch (conditional or unconditional) or a return is a leader
- For each leader, its basic block is the leader and all statements up to, but not including, the next leader or the end of the program

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Example

(1) $i := m - 1$	(16) $t7 := 4 * i$
(2) $j := n$	(17) $t8 := 4 * j$
(3) $t1 := 4 * n$	(18) $t9 := a[t8]$
(4) $v := a[t1]$	(19) $a[t7] := t9$
(5) $i := i + 1$	(20) $t10 := 4 * j$
(6) $t2 := 4 * i$	(21) $a[t10] := x$
(7) $t3 := a[t2]$	(22) $goto(5)$
(8) $if\ t3 < v\ goto(5)$	(23) $t11 := 4 * i$
(9) $j := j - 1$	(24) $x := a[t11]$
(10) $t4 := 4 * j$	(25) $t12 := 4 * i$
(11) $t5 := a[t4]$	(26) $t13 := 4 * n$
(12) $if\ t5 > v\ goto(9)$	(27) $t14 := a[t13]$
(13) $if\ i >= j\ goto(23)$	(28) $a[t12] := t14$
(14) $t6 := 4 * i$	(29) $t15 := 4 * n$
(15) $x := a[t6]$	(30) $a[t15] := x$

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Example: Leaders

(1) $i := m - 1$	(16) $t7 := 4 * i$
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Example: Basic Blocks

(1) $i := m - 1$	(16) $t7 := 4 * i$
(2) $j := n$	(17) $t8 := 4 * j$
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Generating CFGs

- Partition intermediate code into basic blocks
- Add edges corresponding to control flows between blocks
 - Unconditional goto
 - Conditional branch – multiple edges
 - Sequential flow – control passes to the next block (if no branch at the end)
- If no unique entry node n_0 or exit node n_f , add dummy nodes and insert necessary edges
 - Ideally no edges entering n_0 ; no edges exiting n_f
 - Simplify many analysis and transformation algorithms

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Example: CFG

(1) $i := m - 1$	(16) $t7 := 4 * i$
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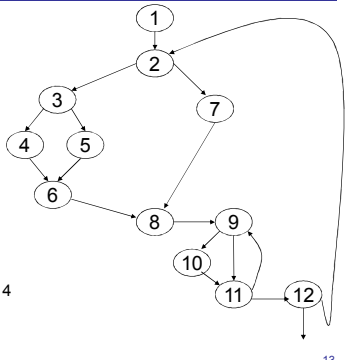
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CFG and HL code

```

I = 1
J = 1
K = 1
L = 1
repeat
  if (P) then begin
    J = I
    if (Q) then L = 2
    else L = 3
    K = K + 1
  end
  else K = K + 2
  print (I,J,K,L)
  repeat
    if (R) then L = L + 4
  until (S)
  I = I + 6
until (T)
    
```



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Complications in CFG Construction

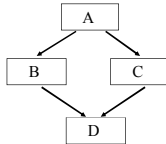
- Function calls
 - Instruction scheduling may prefer function calls as basic block boundaries
 - Special functions as setjmp() and longjmp()
- Exception handling
- Ambiguous jump
 - Jump r1 //target stored in register r1
 - Static analysis may generate edges that never occur at runtime
 - Record potential targets if possible
- Jumps target outside the current procedure
 - PASCAL, Algol: still restricted to lexically enclosing procedure

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Nodes in CFG

- Given a CFG = $\langle N, E \rangle$
 - If there is an edge $n_i \rightarrow n_j \in E$
 - n_i is a predecessor of n_j
 - n_j is a successor of n_i
 - For any node $n \in N$
 - $Pred(n)$: the set of predecessors of n
 - $Succ(n)$: the set of successors of n
 - A branch node is a node that has more than one successor
 - A join node is a node that has more than one predecessor



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Depth First Traversal

- CFG is a rooted, directed graph
 - Entry node as the root
- Depth-first traversal (depth-first searching)
 - Idea: start at the root and explore as far/deep as possible along each branch before backtracking
 - Can build a spanning tree for the graph
- Spanning tree of a directed graph G contains all nodes of G such that
 - There is a path from the root to any node reachable in the original graph and
 - There are no cycles

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DFS Spanning Tree Algorithm

```

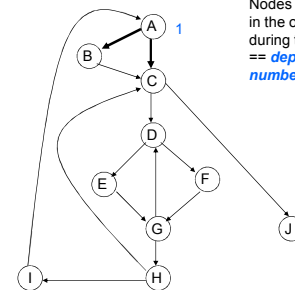
procedure span(v) /* v is a node in the
graph */
  InTree(v) = true
  For each w that is a successor of v do
    if (!InTree(w)) then
      Add edge v → w to spanning tree
      span(w)
end span
    
```

- Initial: $span(n_0)$

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DFST Example

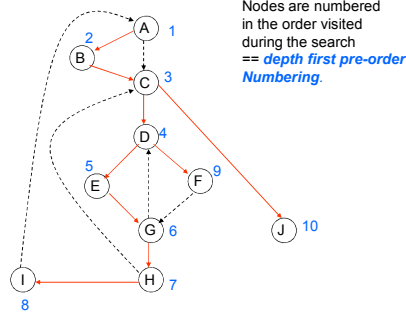


Nodes are numbered in the order visited during the search == depth first pre-order numbering.

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DFST Example



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CFG Edges Classification

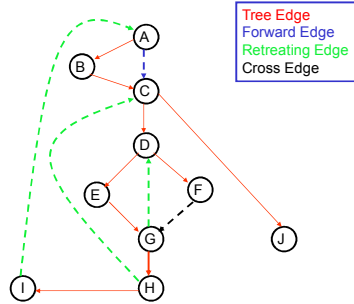
Edge $x \rightarrow y$ in a CFG is an

- **Advancing edge** – if x is an ancestor of y in the tree
 - **Tree edge** – if part of the spanning tree
 - **Forward edge** – if not part of the spanning tree and x is an ancestor of y in the tree
- **Retreating edge** – if not part of the spanning tree and y is an ancestor of x in the tree
- **Cross edge** – if not part of the spanning tree and neither is an ancestor of the other

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DFST Example



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Back Edges and Reducibility

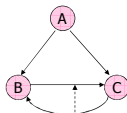
- An edge $x \rightarrow y$ in a CFG is a **back edge** if every path from the entry node of the flow graph to x goes through y
 - y dominates x : more details later
 - Every back edge is a retreating edge
 - Vice versa?
- A flow graph is **reducible** if all its retreating edges in any DFST are also back edges
 - Flow graphs that occur in practice are almost always reducible

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Non-Reducible Graphs

- Testing reducibility: Take any DFST for the flow graph, remove the back edges, and check that the result is acyclic



In any DFST, one of these edges will be a retreating edge

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Nodes Ordering wrt DFST

- Enhanced depth-first spanning tree algorithm:

```
time = 0;
procedure span(v) /* v is a node in the graph */
  InTree(v) = true; d[v] = ++time;
  For each w that is a successor of v do
    if (!InTree(w)) then
      Add edge v → w to spanning tree
      span(w)
  f[v] = ++time;
end span
```

- Associate two numbers to each node v in the graph
 - $d[v]$: **discovery time** of v in the spanning
 - $f[v]$: **finish time** of v in the spanning

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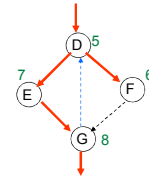
Nodes Ordering wrt DFST

- Pre-ordering
 - Ordering of vertices based on discovery time
- Post-ordering
 - Ordering of vertices based on finish time
- Reverse post-ordering
 - The reverse of a post-ordering, i.e. ordering of vertices in the opposite order of their finish time
 - Not the same as pre-ordering
 - Commonly used in forward data flow analysis
 - Backward data flow analysis: RPO on the reverse CFG

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Ordering Example



- Pre-ordering: DEGF
- Post-ordering: GEFD
- Reverse post-ordering: DFEG

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Big Picture

Why care about ordering / back edges?

- CFGs are commonly used to propagate information between nodes (basic blocks)
 - Data flow analysis
- The existence of back edges / cycles in flow graphs indicates that we may need to traverse the graph more than once
 - Iterative algorithms: when to stop? How quickly can we stop?
- Proper ordering of nodes during iterative algorithm assures number of passes limited by the number of "nested" back edges

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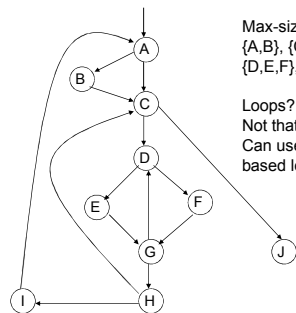
Regions in CFG

- Extended basic block (EBB)
 - EBB is a maximal set of nodes in a CFG that contains no join nodes other than the entry node
 - A single entry and possibly multiple exits
 - Some optimizations like value numbering and instruction scheduling are more effective if applied in EBBs
- Natural loop
 - Loop is a collection of nodes in a CFG such that
 - All nodes in the collection are strongly connected, and
 - The collection of nodes has a unique *entry*: the only way to visit the loop from outside
 - A loop that contains no other loops is an *inner loop*
 - Main target of program optimizations

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EBB Example



Max-size EBBs:
{A,B}, {C,J},
{D,E,F}, {G,H,I}

Loops?
Not that obvious...
Can use dominator-
based loop detection

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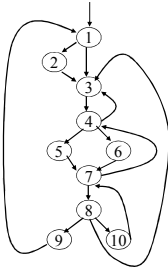
Dominance

- Node d of a CFG *dominates* node n if every path from the entry node of the graph to n passes through d ($d \text{ dom } n$)
 - $\text{Dom}(n)$: the set of dominators of node n
 - Every node dominates itself: $n \in \text{Dom}(n)$
 - Node d strictly dominates n if $d \in \text{Dom}(n)$ and $d \neq n$
 - Dominance-based loop recognition: entry of a loop dominates all nodes in the loop
- Each node n has a unique *immediate dominator* m which is the last dominator of n on any path from the entry to n ($m \text{ idom } n$), $m \neq n$
 - The immediate dominator m of n is the strict dominator of n that is closest to n

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Dominator Example

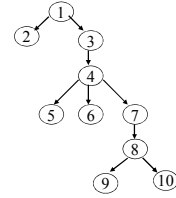
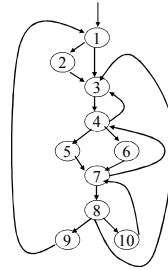


Block	Dom	IDom
1	{1}	—
2	{1,2}	1
3	{1,3}	1
4	{1,3,4}	3
5	{1,3,4,5}	4
6	{1,3,4,6}	4
7	{1,3,4,7}	4
8	{1,3,4,7,8}	7
9	{1,3,4,7,8,9}	8
10	{1,3,4,7,8,10}	8

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Dominator Trees

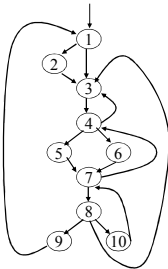


- In a dominator tree, a node's parent is its immediate dominator

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Other sets of interest

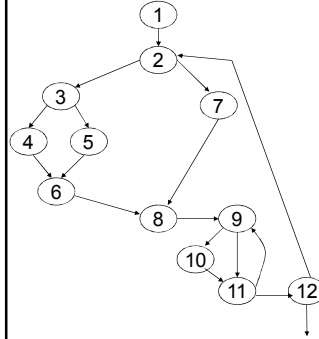


Block	SDom	Dom ⁻¹
1	{}	{1,2,3,4,5,6,7,8,9,10}
2	{1}	{2}
3	{1}	{3,4,5,6,7,8,9,10}
4	{1,3}	{4,5,6,7,8,9,10}
5	{1,3,4}	{5}
6	{1,3,4}	{6}
7	{1,3,4}	{7,8,9,10}
8	{1,3,4,7}	{8,9,10}
9	{1,3,4,7,8}	{9}
10	{1,3,4,7,8}	{10}

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Example 2

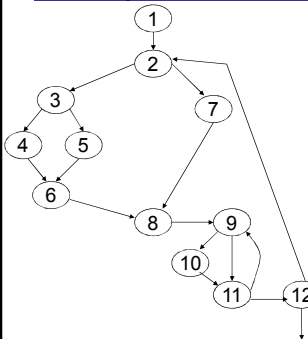


Block	Dom	IDom
1		
2		
3		
4		
5		
6		
7		
8		
9		
10		
11		
12		

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Example 2



Block	Dom	IDom
1	1	-
2	1,2	1
3	1,2,3	2
4	1,2,3,4	3
5	1,2,3,5	3
6	1,2,3,6	3
7	1,2,7	2
8	1,2,8	2
9	1,2,8,9	8
10	1,2,8,9,10	9
11	1,2,8,9,11	9
12	1,2,8,9,11,12	11

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Algorithm: Computing DOM

- An iterative fixed-point calculation

N is the set of nodes in the CFG

$DOM(n_0) = \{n_0\}$ (n_0 is the entry)

For all nodes $x \neq n_0$

$DOM(x) = N$

Until no more changes to dominator sets

for all nodes $x \neq n_0$

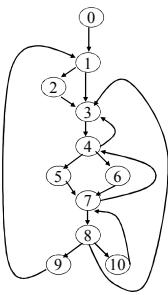
$DOM(x) = \{x\} + (\cap DOM(P))$ for all predecessors P of x

- At termination, node d in $DOM(n)$ iff d dominates n

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Dominator Example

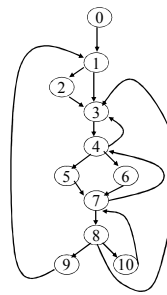


	initial	iteration1
0	{0}	{0}
1	N	{1} + (Dom(0) ∩ Dom(9)) = {0,1}
2	N	{2} + Dom(1) = {0,1,2}
3	N	{3} + (Dom(1) ∩ Dom(2) ∩ Dom(8) ∩ Dom(4)) = {0,1,3}
4	N	{4} + (Dom(3) ∩ Dom(7)) = {0,1,3,4}
5	N	{5} + Dom(4) = {0,1,3,4,5}
6	N	{6} + Dom(4) = {0,1,3,4,6}
7	N	{7} + (Dom(5) ∩ Dom(6) ∩ Dom(10)) = {0,1,3,4,7}
8	N	{8} + Dom(7) = {0,1,3,4,7,8}
9	N	{9} + Dom(8) = {0,1,3,4,7,8,9}
10	N	{10} + Dom(8) = {0,1,3,4,7,8,10}

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Dominator Example



Block	Dom		
	initial	iteration1	iteration2
0	{0}	{0}	{0}
1	N	{0,1}	{0,1}
2	N	{0,1,2}	{0,1,2}
3	N	{0,1,3}	{0,1,3}
4	N	{0,1,3,4}	{0,1,3,4}
5	N	{0,1,3,4,5}	{0,1,3,4,5}
6	N	{0,1,3,4,6}	{0,1,3,4,6}
7	N	{0,1,3,4,7}	{0,1,3,4,7}
8	N	{0,1,3,4,7,8}	{0,1,3,4,7,8}
9	N	{0,1,3,4,7,8,9}	{0,1,3,4,7,8,9}
10	N	{0,1,3,4,7,8,10}	{0,1,3,4,7,8,10}

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Computing IDOM from DOM

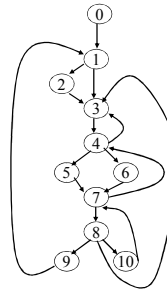
- For each node n , initially set $IDOM(n) = DOM(n) - \{n\}$ (SDOM - strict dominators)
- For each node p in $IDOM(n)$, see if p has dominators other than itself also included in $IDOM(n)$: if so, remove them from $IDOM(n)$

- The immediate dominator m of n is the strict dominator of n that is closest to n

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I-Dominator Example



Block	IDom	
	initial (SDOM)	
0	{}	{}
1	{0}	{0}
2	{0,1}	{1} // 0 - 1's dominator
3	{0,1}	{1} // 0 - 1's dominator
4	{0,1,3}	{3} // 0, 1 - 3's dominators
5	{0,1,3,4}	{4} // 0, 1, 3 - 4's dominators
6	{0,1,3,4}	{4} // 0, 1, 3 - 4's dominators
7	{0,1,3,4}	{4} // 0, 1, 3 - 4's dominators
8	{0,1,3,4,7}	{7} // 0, 1, 3, 4 - 7's dominators
9	{0,1,3,4,7,8}	{8} // 0, 1, 3, 4, 7 - 8's dominators
10	{0,1,3,4,7,8}	{8} // 0, 1, 3, 4, 7 - 8's dominators

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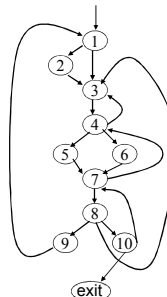
Post-Dominance

- Related concept
- Node d of a CFG *post-dominates* node n if every path from n to the exit node passes through d ($d \text{ pdom } n$)
 - $Pdom(n)$: the set of post-dominators of node n
 - Every node post-dominates itself: $n \in Pdom(n)$
- Each node n has a unique *immediate post dominator* m

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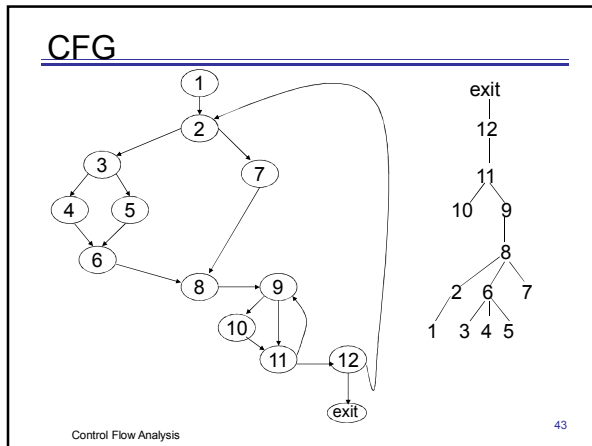
Post-dominator Example



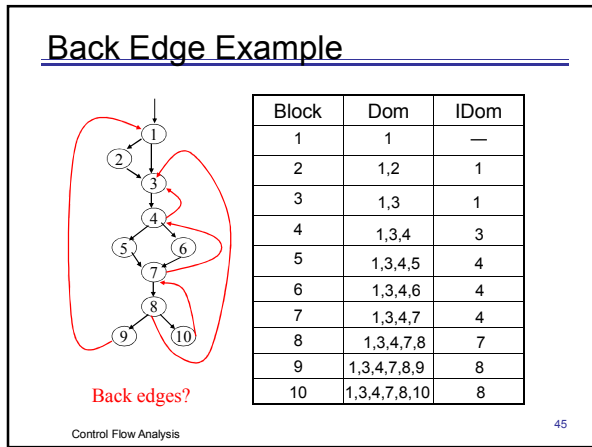
Block	Pdom	IPdom
1	{3,4,7,8,10,exit}	3
2	{2,3,4,7,8,10,exit}	3
3	{3,4,7,8,10,exit}	4
4	{4,7,8,10,exit}	7
5	{5,7,8,10,exit}	7
6	{6,7,8,10,exit}	7
7	{7,8,10,exit}	8
8	{8,10,exit}	10
9	{1,3,4,7,8,10,exit}	1
10	{10,exit}	exit

Control Flow Analysis

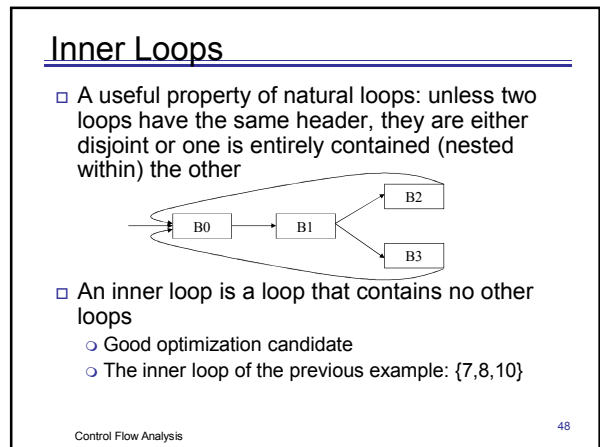
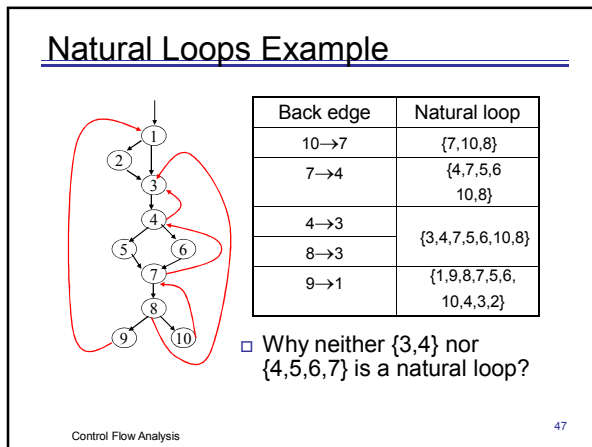
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- ### Natural Loops
- Natural loops that are suitable for improvement have two essential properties:
 - A loop must have a single entry point called *header*
 - There must be at least one way to iterate the loop, i.e., at least one path back to the header
 - Identifying natural loops
 - Searching for **back edges** ($n \rightarrow d$) in CFG whose heads *dominate* their tails
 - For an edge $a \rightarrow b$, b is the *head* and a is the *tail*
 - A back edge flows from a node n to one of n 's dominators d
 - The natural loop for that edge is $\{d\}$ +the set of nodes that can reach n without going through d
 - d is the header of the loop
- Control Flow Analysis 44



- ### Identifying Natural Loops
- Given a back edge $n \rightarrow d$, the natural loop of the edge includes
 - Node d
 - Any node that can reach n without going through d
 - Loop construction
 - Set $loop = \{d\}$
 - Add n into $loop$ if $n \neq d$
 - Consider each node $m \neq d$ that we know is in $loop$, make sure that m 's predecessors are also inserted in $loop$
- Control Flow Analysis 46



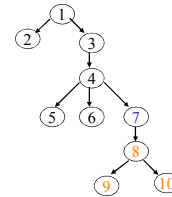
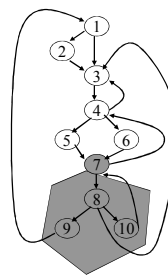
Dominance Frontiers

- For a node n in CFG, $DF(n)$ denotes the **dominance frontier** set of n
 - $DF(n)$ contains all nodes x s.t. n dominates an immediate predecessor of x but does not strictly dominate x
 - For this to happen, there is some path from node n to x , $n \rightarrow \dots \rightarrow y \rightarrow x$ where $(n \text{ DOM } y)$ but $!(n \text{ SDOM } x)$
 - Informally, $DF(n)$ contains the first nodes reachable from n that n does not strictly dominate, on each CFG path leaving n
- Used in SSA calculation and redundancy elimination

Control Flow Analysis

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Dominance Frontier for Node 7

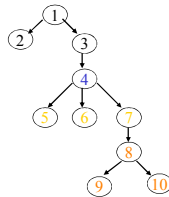
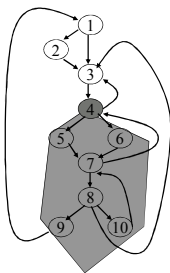


Paths of interest:
 $7 \rightarrow 4$
 $7 \rightarrow 8 \rightarrow 3$
 $7 \rightarrow 8 \rightarrow 9 \rightarrow 1$
 $7 \rightarrow 8 \rightarrow 10 \rightarrow 7$
 $DF(7) = \{1, 3, 4, 7\}$

Control Flow Analysis

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Dominance Frontier for Node 4



Paths of interest:
 $DF(4) = \{1, 3, 4\}$

Control Flow Analysis

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Computing Dominance Frontiers

- Easiest way:
 $DF(x) = \text{SUCC}(\text{DOM}^{-1}(x)) - \text{SDOM}^{-1}(x)$ where
 $\text{SUCC}(x)$ = set of successors of x in the CFG
 - But not the most efficient
- Observation
 - Nodes in a DF must be join nodes
 - The predecessor of any join node j must have j in its DF unless it dominates j
 - The dominators of j 's predecessors must have j in their DF sets unless they also dominate j

Control Flow Analysis

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Computing Dominance Frontiers

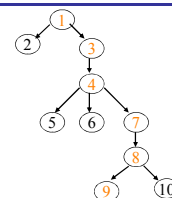
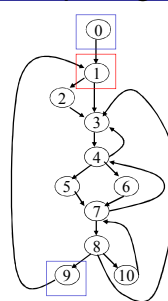
for all nodes n , initialize $DF(n) = \emptyset$
for all nodes n
if n has multiple predecessors, then
for each predecessor p of n
runner = p
while (runner \neq IDom(n))
 $DF(\text{runner}) = DF(\text{runner}) \cup \{n\}$
runner = IDom(runner)

- First identify join nodes j in CFG
- Starting with j 's predecessors, walk up the dominator tree until we reach the immediate dominator of j
 - Node j should be included in the DF set of all the nodes we pass by except for j 's immediate dominator

Control Flow Analysis

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Computing Dominance Frontier

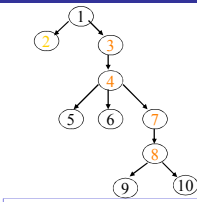
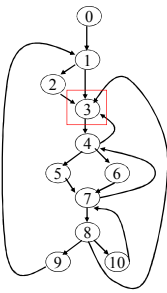


Join node 1:
runner = 0 = IDom(1)
runner = 9 : $DF(9) += \{1\}$
runner = 8 : $DF(8) += \{1\}$
runner = 7 : $DF(7) += \{1\}$
runner = 4 : $DF(4) += \{1\}$
runner = 3 : $DF(3) += \{1\}$
runner = 1 : $DF(1) += \{1\}$
runner = 0 = IDom(1)

Control Flow Analysis

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Computing Dominance Frontier

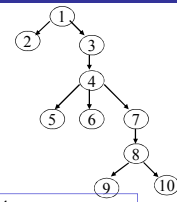
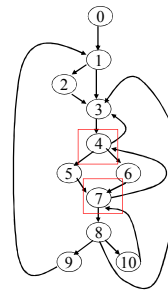


Join node 3:
 runner = 1 = IDom(3)
 runner = 2: DF(2) += {3}
 runner = 4: DF(4) += {3}
 runner = 3: DF(3) += {3}
 runner = 8: DF(8) += {3}
 runner = 7: DF(7) += {3}

Control Flow Analysis

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Computing Dominance Frontier



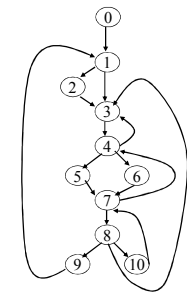
Join node 4:
 runner = 3 = IDom(4)
 runner = 7: DF(7) += {4}
 runner = 4: DF(4) += {4}

Join node 7:
 runner = 5: DF(5) += {7}
 runner = 6: DF(6) += {7}
 runner = 10: DF(10) += {7}
 runner = 8: DF(8) += {7}
 runner = 7: DF(7) += {7}

Control Flow Analysis

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Dominance Frontier Example

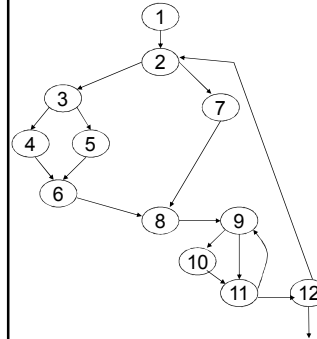


Block	DF
1	{1}
2	{3}
3	{1,3}
4	{1,3,4}
5	{7}
6	{7}
7	{1,3,4,7}
8	{1,3,7}
9	{1}
10	{7}

Control Flow Analysis

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Example 2



Bloc k	DF
1	
2	
3	
4	
5	
6	
7	
8	
9	
10	
11	
12	

Control Flow Analysis

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Dominator-based Analysis

- Idea
 - Use dominators to discover loops for optimization
- Advantages
 - Sufficient for use by iterative data-flow analysis and optimizations
 - Least time-intensive to implement
 - Favored by most current optimizing compilers
- Alternative approach
 - Interval-based analysis/structural analysis

Control Flow Analysis

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Summary

- CFG construction
 - Basic blocks identification
- CFG traversal
 - Depth-first spanning tree
 - Vertex ordering
- CFG analysis
 - Important regions: EBB and loop
 - Dominators
 - Dominance frontiers
- Additional references
 - Advanced compiler design and implementation, by S. Muchnick, Morgan Kaufmann

Control Flow Analysis

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